

ON A SMOOTH QUARTIC SURFACE CONTAINING 56 LINES
WHICH IS ISOMORPHIC AS A $K3$ SURFACE TO
THE FERMAT QUARTIC: COMPUTATIONAL DATA

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1. INTRODUCTION

We give an explanation of the computational data that are used in the paper [X56]. I. Shimada and T. Shioda: On a smooth quartic surface containing 56 lines which is isomorphic as a $K3$ surface to the Fermat quartic, <http://www.math.sci.hiroshima-u.ac.jp/~shimada/preprints.html>

and available from the author's webpage

<http://www.math.sci.hiroshima-u.ac.jp/~shimada/K3.html>.

All data is written on a single text file `X56compdata.txt` (13.6 MB). The complex number

$$\zeta = \exp(2\pi\sqrt{-1}/8)$$

is expressed as `zeta`. We use the same notation as [X56].

2. EXPLANATION OF THE COMPUTATIONAL DATA

2.1. The lines on X_{48} .

- `LineTags48` The list of tags of the 48 lines on X_{48} .
- `LineEqs48` The list of equations of the 48 lines on X_{48} , which is sorted according to `LineTags48`. The k th equation is given as a 2×4 matrix M_k with components in $\mathbb{Q}(\zeta)$ in the row-reduced echelon form, and the k th line is defined by $M_k x = 0$, where $x = [x_1, x_2, x_3, x_4]^T$.
- `LineIntNumbs48` The 48×48 matrix of the intersection numbers of lines on X_{48} . The rows and columns are sorted according to `LineTags48`.
- `BasisSX` The tags of the 20 lines $[l_1], \dots, [l_{20}]$ that form a basis of S_X .
- `GramSX` The Gram matrix G_{S_X} of S_X with respect to the basis $[l_1], \dots, [l_{20}]$ of S_X .
- `h48` The class h_{48} .
- `LineClasses48` The list \mathcal{F}_{48} of classes of lines on X_{48} , which is sorted according to `LineTags48`.
- `taupoints` The list of τ -points.

In the following, the i th line ℓ_i on X_{48} means the line labelled by the i th tag in `LineTags48`.

- `basisnumbs48` A list $[i_1, \dots, i_{20}]$ such that the classes $[\ell_{i_j}]$ of the i_j th line on X_{48} form a basis of S_X .

2.2. The lattice S_X .

- **discSXreps** The vectors s_1 and s_2 of S_X^\vee in the dual representation.
- **discSX** The discriminant form with respect to the basis σ_1, σ_2 of $\text{disc}(S_X)$.
- **discSXproj** The matrix P that expresses the projection $S_X^\vee \rightarrow \text{disc}(S_X)$ with respect to the dual basis of S_X^\vee and the basis σ_1, σ_2 of $\text{disc}(S_X)$.
- **OqSX** The group $O(q_{S_X})$.
- **GramT** The Gram matrix of T with respect to the basis t_1, t_2 .
- **discTreps** The vectors t_1^\vee and t_2^\vee of T^\vee in the dual representation, that is, $[1, 0]$ and $[0, 1]$.
- **discT** The discriminant form with respect to the basis τ_1, τ_2 of $\text{disc}(T)$.
- **discTproj** The matrix that expresses the projection $T^\vee \rightarrow \text{disc}(T)$ with respect to the dual basis t_1^\vee, t_2^\vee of T^\vee and the basis τ_1, τ_2 of $\text{disc}(T)$.
- **OT** The group $O(T)$.
- **OqT** The group $O(q_T)$.
- **GammatildeT** The group $\tilde{\Gamma}_T$.
- **etaGammatildeT** The subgroup $\eta_T(\tilde{\Gamma}_T)$ of $O(q_T)$.
- **Isoms** The list of isomorphisms from q_{S_X} to $-q_T$.
- **GammaSX** The subgroup Γ_{S_X} of $O(q_{S_X})$.

2.3. The groups associated with X_{48} .

- **Gtilde48** The group \tilde{G}_{48} as a list of 20×20 matrices in $O(S_X)$.
- **Gtilde48Perms** The group \tilde{G}_{48} as a list of permutations on \mathcal{F}_{48} . An element $[i_1, \dots, i_{48}]$ of this list maps the class $[\ell_j]$ to the class of $[\ell_{i_j}]$ for $j = 1, \dots, 48$. The list **Gtilde48Perms** is sorted according to the list **Gtilde48**.
- **G48** The group G_{48} as a list of 20×20 matrices in $O(S_X)$.
- **G48Perms** The group G_{48} as a list of permutations on \mathcal{F}_{48} . The list **G48Perms** is sorted according to the list **G48**.
- **Gal** The group $\text{Gal}(\mathbb{Q}(\zeta)/\mathbb{Q})$ as a subgroup of **Gtilde48**.
- **GalPerms** The group $\text{Gal}(\mathbb{Q}(\zeta)/\mathbb{Q})$ as a subgroup of **Gtilde48Perms**. The list **GalPerms** is sorted according to the list **Gal**.

2.4. The orbit decomposition of the set of pairs of lines on X_{48} by G_{48} .

- **OrbitsOfPairs** The list of the orbits o_1, \dots, o_8 . Each orbit is a list of pairs $[i, j]$, which denote the pairs $\{\ell_i, \ell_j\}$.
- **OrbitsMat** The 48×48 matrix whose (i, j) component is k if $\{\ell_i, \ell_j\} \in o_k$ and 0 if $i = j$.
- **Aos** The list of the matrices $A(o_1), \dots, A(o_8)$.

2.5. **The sets \mathcal{H}_5 and \mathcal{H}_6 .** The lists **H5reps** and **H6reps** are the list of orbits in the sets \mathcal{H}_5 and \mathcal{H}_6 under the action of G_{48} . Each list consists of the data

$$[v, \text{size}, \text{flags}],$$

where v is a representative of the orbit, **size** is the size of the orbit, and **flags** has the following meaning:

- if **flags** is **[false]**, then v is not nef,
- if **flags** is **[true, false]**, then v is nef, but $|\mathcal{L}_v|$ has a fixed-component,
- if **flags** is **[true, true, false]**, then v is nef, $|\mathcal{L}_v|$ is fixed-component free, but the morphism $\Phi_v: X_{48} \rightarrow \mathbb{P}^3$ is hyperelliptic,

- if `flags` is `[true, true, true, false, R]`, then v is nef, $|\mathcal{L}_v|$ is fixed-component free, $\Phi_v: X_{48} \rightarrow \mathbb{P}^3$ is non-hyperelliptic, but the image X_v of Φ_v has singularities of *ADE*-type R (for example, $R = ["A1", "A1"]$ means that X_v has two ordinary nodes as its only singularities), and
- if `flags` is `[true, true, true, true, n]`, then v is very ample and X_v contains exactly n lines.

The representative element v of an orbit is chosen so that the vector representation of v with respect to the basis $[l_1], \dots, [l_{20}]$ of S_X is minimal with respect to the lexicographic order.

2.6. The surface X_{56} .

- `X56Pols` The list of X_{56} -polarizations. This list consists of two lists of size 192, each of which is an orbit under the action of G_{48} .
- `X56ConfigOrbitsMat` The 7×7 matrix that defines the X_{56} -configuration; that is, a 7-tuple $(\ell'_1, \dots, \ell'_7)$ of lines on X_{48} is an X_{56} -configuration if $\{\ell'_i, \ell'_j\}$ is in o_k for $i, j = 1, \dots, 7$ with $i \neq j$, where k is the (i, j) component of `X56ConfigOrbitsMat`. (The diagonal components of `X56ConfigOrbitsMat` are set to be 0.)
- `X56Configs` The list of X_{56} -configurations. Each member is an ordered list $[i_1, \dots, i_7]$, which indicates the list $(\ell_{i_1}, \dots, \ell_{i_7})$ of seven lines on X_{48} that form an X_{56} -configuration.
- `TheX56Config` The fixed X_{56} -configuration $(\ell_1, \ell_{11}, \ell_3, \ell_{17}, \ell_{22}, \ell_{36}, \ell_{18})$ that gives the X_{56} -polarization h_{56} , given as $[1, 11, 3, 17, 22, 36, 18]$. See (4.2) of [X56].
- `h56` The class h_{56} .
- `A` $A = -1 - 2\zeta - 2\zeta^3$.
- `B` $B = 2 - 2\zeta - 2\zeta^3$.
- `Psi` The equation Ψ .
- `fPolys` The homogeneous cubic polynomials f_1, \dots, f_4 in `x1, x2, x3, x4`.

The following are the data used in the proof of Theorem 4.6 in [X56].

- `BasisGamma3` The basis of the 20-dimensional linear space Γ_3 , consisting of monomials in `x1, x2, x3, x4` of degree 3.
- `M56` The 24×20 matrix \mathcal{M}_{56} such that the solution space of the linear equation $\mathcal{M}_{56}z = 0$ defines the 4-dimensional subspace $H^0(X, \mathcal{L}_{h_{56}})$ of Γ_3 with respect to the basis `BasisGamma3`.
- `fVects` The basis f_1, \dots, f_4 of the solution space of $\mathcal{M}_{56}z = 0$, written as row vectors with respect to the basis `BasisGamma3`.
- `BasisbarGamma12` A basis of the 290-dimensional linear space $\bar{\Gamma}_{12}$, consisting of monomials in `x1, x2, x3, x4` of degree 12 with the degree with respect to `x1` is ≤ 3 .
- `BasisSigma4` A basis of the 35-dimensional linear space Σ_4 , consisting of monomials in `y1, y2, y3, y4` of degree 4.
- `rhosigma` The 290×35 matrix representing the linear map $\rho \circ \sigma: \Sigma_4 \rightarrow \bar{\Gamma}_{12}$ with respect to the bases `BasisSigma4` and `BasisbarGamma12`.
- `PsiVect` The equation $\Psi \in \Sigma_4$ represented as a row vector with respect to the basis `BasisSigma4` of Σ_4 .

2.7. The lines on X_{56} .

- **LineClasses56** The list \mathcal{F}_{56} of classes of lines on X_{56} . The lines on X_{56} are sorted according to this list, that is, the k th line on X_{56} means the line on X_{56} whose class is the k th vector of **LineClasses56**.
- **LineIntNums56** The 56×56 matrix of the intersection numbers of lines on X_{56} . The rows and columns are sorted according to **LineClasses56**.
- **LineEqs56** The list of equations of the 56 lines on X_{56} . The k th equation is given as a 2×4 matrix M_k with components in $\mathbb{Q}(\zeta)$ in the row-reduced echelon form, and the k th line is defined by $M_k y = 0$, where $y = [y_1, y_2, y_3, y_4]^T$.

2.8. The groups associated with X_{56} .

- **basisnums56** A list $[i_1, \dots, i_{20}]$ such that the classes of the i_j th line on X_{56} form a basis of S_X .
- **Gtilde56** The group \tilde{G}_{56} as a list of 20×20 matrices in $O(S_X)$.
- **Gtilde56Perms** The group \tilde{G}_{56} as a list of permutations on \mathcal{F}_{56} . An element $[i_1, \dots, i_{56}]$ of this list maps the class of the j th line on X_{56} (that is, the j th vector of **LineClasses56**) to the class of the i_j th line on X_{56} (that is, the i_j th vector of **LineClasses56**) for $j = 1, \dots, 56$. The list **Gtilde56Perms** is sorted according to the list **Gtilde56**.
- **G56** The group G_{56} as a list of 20×20 matrices in $O(S_X)$.
- **G56Perms** The group G_{56} as a list of permutations on \mathcal{F}_{56} . The list **G56Perms** is sorted according to the list **G56**.
- **G56PGL** The group G_{56} as a list of elements of $\text{PGL}_3(\mathbb{C})$. The list **G56PGL** is sorted according to the list **G56Perms**, in the sense that, for the i th element g of **G56PGL**, the mapping $[\lambda] \mapsto [g(\lambda)]$ induces the i th permutation in **G56Perms**. CAUTION: Hence the representation of the i th element g of **G56PGL** on S_X is *not* the i th element f of **G56**, but its inverse f^{-1} , because the representation is defined by the pull-back.
- **GeneratorsG56** A set of generators of **G56** consisting of two elements.
- **GeneratorsG56Perms** The generators of **G56Perms** corresponding the two elements in **GeneratorsG56**.
- **GeneratorsG56PGL** The generators of **G56PGL** corresponding the two elements in **GeneratorsG56**. These two matrices are γ_1 and γ_2 in Theorem 4.9 of [X56].
- **OrbitsLines56** The orbit decomposition of lines on X_{56} under the action of G_{56} . Each orbit is a list $[i_1, \dots, i_t]$, which denote the orbit consisting of the i_j th lines for $j = 1, \dots, t$.

2.9. The reductions.

- **PsivarA** The equation Ψ with A written as **varA** and B written as **varA+3**.
- **F56prime** The subset \mathcal{F}'_{56} of S_X^\vee . Each element is given as a row vector with respect to the basis $[l_1], \dots, [l_{20}]$ of S_X .

2.10. The reduction at P_3 .

- **LineEqs56P3** The list of $[M_\lambda, U_\lambda, \overline{U_\lambda M_\lambda}]$, where M_λ is the defining matrix of a line λ on X_{56} given in **LineEqs56**, and U_λ is a 2×2 invertible matrix with components in $\mathbb{Q}(\zeta)$ such that

$$\overline{U_\lambda M_\lambda} := U_\lambda M_\lambda \bmod P_3$$

is a matrix of rank 2 in the row-reduced echelon form with components in $\kappa_{P_3} \cong \mathbb{F}_9$. The $\gamma = \mathbf{gamma}$ that appears in $\overline{U_\lambda M_\lambda}$ is a 8th root of unity in \mathbb{F}_9 such that $A \bmod P_3 = -1 - 2\gamma - 2\gamma^3$ is zero, that is, $\gamma \in \mathbb{F}_9$ is a root of $\gamma^2 + 2\gamma + 2 = 0$.

- **LineEqs112P3** The list of defining equations of the 112 lines on $X_{56}(P_3)$. The equations in the second half of this list come from the reduction (that is, they appear as the third members of elements of **LineEqs56P3**), while those in the first half are new (that is, they define the unique common intersecting lines of $\Lambda(r') \otimes \kappa_{P_3}$ of $r' \in \mathcal{F}'_{56}$).

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