# The space of left-invariant metrics — on a generalization of Milnor frames

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## **0** Abstract

We are studying:

• the existence and nonexistence problems of

distinguished left-invariant metrics on Lie groups,

• by a generalization of Milnor frames (Milnor-type theorems).

**Contents:** 

- **§1: Introduction**
- **§2:** Results (for Riemannian case)
- **§3: Results (for pseudo-Riemannian case)**
- **§4: Summary and Problems**

## **1** Introduction

## §1.1 Contents

**Recall that we are studying:** 

• the existence and nonexistence problems of

distinguished left-invariant metrics on Lie groups,

• by a generalization of Milnor frames (Milnor-type theorems).

**Contents of this section:** 

- **§1.2:** Distinguished left-invariant metrics
- **§1.3:** The existence and nonexistence problem
- **§1.4: (Classical) Milnor frames**
- **§1.5:** What are Milnor-type theorems?

§1.2 Distinguished left-invariant metrics (1/2)

#### **Our theme:**

• Left-invariant Riemannian metrics g on Lie groups G.

They can be studied in terms of:

- $(\mathfrak{g}, \langle, \rangle)$ : the corresponding metric Lie algebras.
- The Levi-Civita connection  $\nabla : \mathfrak{g} \times \mathfrak{g} \to \mathfrak{g}$  satisfies  $2\langle \nabla_X Y, Z \rangle = \langle [X, Y], Z \rangle + \langle [Z, X], Y \rangle + \langle X, [Z, Y] \rangle.$

They provide examples of:

- **Einstein** :  $\Leftrightarrow$  Ric =  $c \cdot id$  ( $\exists c \in \mathbb{R}$ ),
- algebraic Ricci soliton

: $\Leftrightarrow$  Ric =  $c \cdot id + D$  ( $\exists c \in \mathbb{R}, \exists D \in Der(g)$ ),

• Ricci soliton :  $\Leftrightarrow$  ric =  $cg + \mathfrak{L}_X g$  ( $\exists c \in \mathbb{R}, \exists X \in \mathfrak{X}(G)$ ).

(Fact: Einstein ⇒ algebraic Ricci soliton ⇒ Ricci soliton)

## **§1.2** Distinguished left-invariant metrics (2/2)

#### **Example (Heisenberg Lie algebra):**

• 
$$\mathfrak{h}^3 := \operatorname{span}\{e_1, e_2, e_3\}$$
 with  $[e_1, e_2] = e_3$ ,  $[e_1, e_3] = [e_2, e_3] = 0$ .
•  $\langle , \rangle$  : canonical inner product  $(\{e_1, e_2, e_3\} : \text{o.n.b.})$ 
⇒ • Ric  $= \frac{1}{2} \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ .
• Der( $\mathfrak{h}^3$ )  $= \left\{ \begin{pmatrix} a & * & 0 \\ * & b & 0 \\ \hline * & * & a+b \end{pmatrix} \mid a, b \in \mathbb{R} \right\}$ .
• Hence,  $(\mathfrak{h}^3, \langle, \rangle)$  is an algebraic Ricci soliton (Ric =  $c \cdot \operatorname{id} + D$ ).

$$(\because) \operatorname{Ric} = -\frac{3}{2} \cdot \operatorname{id} + \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}.$$

## **§1.3** The existence and nonexistence problem (1/2)

#### **Problem:**

For a given Lie group G, examine
 whether G admits a distinguished left-invariant metric.
 (e.g., Einstein, (algebraic) Ricci soliton)

**Known results:** 

• Classification for low dimensional ones.

(Einstein when dim  $\leq$  5, alg. Ricci soliton when dim  $\leq$  4, ...)

- Some higher-dimensional examples.
- Far from the complete understanding...

## §1.3 The existence and nonexistence problem (2/2)

#### **Recall the problem:**

• Examine whether G admits a distinguished left-invariant metric.

Note:

- In general, this problem is difficult.
- - $\cong$  {inner products on g}

 $\cong \operatorname{GL}_n(\mathbb{R})/\operatorname{O}(n).$ 

(Note that  $n := \dim G$ , and  $g.\langle \cdot, \cdot \rangle := \langle g^{-1}(\cdot), g^{-1}(\cdot) \rangle$ )

### §1.4 (Classical) Milnor frames (1/2)

#### Thm. (Milnor 1976):

- g: 3-dimensional unimodular
- ⟨, ⟩ : any inner product on g

$$\Rightarrow \exists \{x_1, x_2, x_3\} : \text{o.n.b. w.r.t. } \langle, \rangle, \exists \lambda_1, \lambda_2, \lambda_3 \in \mathbb{R} :$$
$$[x_1, x_2] = \lambda_3 x_3, \ [x_2, x_3] = \lambda_1 x_1, \ [x_3, x_1] = \lambda_2 x_2.$$

#### **Remark:**

- $\{x_1, x_2, x_3\}$  is called the Milnor frame.
- For each g, possible values of  $\lambda_1$ ,  $\lambda_2$ ,  $\lambda_3$  are determined.
- All inner products can be studied by using up to 3 parameters. (Note that  $\widetilde{\mathfrak{M}} = \operatorname{GL}_3(\mathbb{R})/\operatorname{O}(3)$  has dimension 6.)

## §1.4 (Classical) Milnor frames (2/2)

#### **Example:**

$$\langle , \rangle : \text{ any inner product on } \mathfrak{g} := \mathfrak{sl}_2(\mathbb{R}) \Rightarrow \circ \exists \{x_1, x_2, x_3\} : \text{ o.n.b. wrt } \langle , \rangle, \exists \lambda_1 > 0, \lambda_2 > 0, \lambda_3 < 0 : [x_1, x_2] = \lambda_3 x_3, [x_2, x_3] = \lambda_1 x_1, [x_3, x_1] = \lambda_2 x_2.$$

#### Cor.:

- The eigenvalues of  $\operatorname{Ric}_{\langle,\rangle}$  are either (+, -, -) or (0, 0, -).
- $SL_2(\mathbb{R})$  does not admit left-invariant Einstein metrics.

#### **Comment:**

- The Milnor frames are quite useful.
- But, the proof strongly depends on dimension 3...

**§1.5** What are Milnor-type theorems? (1/2)

**Today's topic is:** 

• Milnor-type theorems,

a generalization of Milnor frames to higher-dim. Lie groups.

- A format of Milnor-type theorems:
  - g : a Lie algebra,
  - $\circ$   $\langle, \rangle$  : any inner product on g
    - $\Rightarrow \exists k > 0, \exists \{x_1, \ldots, x_n\} : \text{o.n.b. w.r.t. } k\langle, \rangle :$

the bracket relations contain *l* parameters.

**Comment:** 

• If  $l \ll \dim \widetilde{\mathfrak{M}}$ , then such Milnor-type theorem is useful.

## **§1.5** What are Milnor-type theorems? (2/2)

Thm. (Hashinaga-T.-Terada, preprint):

• For ANY Lie algebra g,

there is a procedure to obtain a Milnor-type theorem for g.

**Applications:** 

- Milnor-type theorems for several Lie groups, and
- (non)existence results of distinguished left-invariant metrics on some Lie groups.

## 2 **Results (for Riemannian case)**

## §2.1 Contents

We have:

- a procedure to obtain Milnor-type theorems,
- and some applications.

**Contents of this section:** 

- **§2.2:** A procedure to obtain Milnor-type theorems
- **§2.3:** Three-dimensional case
- **§2.4:** Higher-dimensional examples

<u>§2.2 A procedure to obtain Milnor-type theorems (1/4)</u> Def.:

•  $\mathfrak{PM} := \mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}) \setminus \widetilde{\mathfrak{M}}$  (the orbit space)

is called the moduli space of left-invariant metrics.

**Recall:** 

- $\widetilde{\mathfrak{M}} := \{\langle, \rangle : \text{ an inner product on } \mathfrak{g}\} \cong \operatorname{GL}_n(\mathbb{R})/\operatorname{O}(n).$
- $\circ \mathbb{R}^{\times} := \{ c \cdot \mathrm{id} : \mathfrak{g} \to \mathfrak{g} \mid c \neq 0 \}.$
- $\operatorname{Aut}(\mathfrak{g}) := \{ \varphi : \mathfrak{g} \to \mathfrak{g} : \text{an automorphism} \}.$
- $\mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}) \frown \widetilde{\mathfrak{M}}$  by  $g.\langle \cdot, \cdot \rangle := \langle g^{-1}(\cdot), g^{-1}(\cdot) \rangle$ .

**Story:** 

- An expression of  $\mathfrak{PM} = \mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}) \setminus \widetilde{\mathfrak{M}}$ 
  - $\Rightarrow$  A "Milnor-type theorem" for g.

§2.2 A procedure to obtain Milnor-type theorems (2/4) Story:

- An expression of  $\mathfrak{PM} = \mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}) \setminus \widetilde{\mathfrak{M}}$ 
  - $\Rightarrow$  A "Milnor-type theorem" for g.

Note:

- $\widetilde{\mathfrak{M}} = \operatorname{GL}_n(\mathbb{R})/\operatorname{O}(n)$ : a noncompact Riemannian symmetric space,
- $\mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}) \curvearrowright \widetilde{\mathfrak{M}}$ : an isometric action.
- There are some general theory on the orbit spaces...

Fact (Berndt-Brück 2002):

- M: a Hadamard manifold (e.g.,  $M = \widetilde{\mathfrak{M}}$ )
- $H \sim M$ : of cohomogeneity one (H: connected)  $\Rightarrow H \setminus M \cong \mathbb{R}$  or  $[0, +\infty)$ .

## §2.2 A procedure to obtain Milnor-type theorems (3/4)

#### Thm. (Hashinaga-T.-Terada, preprint):

- $\{e_1,\ldots,e_n\}$ : o.n.b. of g w.r.t.  $\langle,\rangle_0$
- $\operatorname{GL}_n(\mathbb{R}) \supset \mathfrak{U}$ : a set of representatives of  $\mathfrak{PM}$

(i.e.,  $\{g.\langle,\rangle_0 \mid g \in \mathfrak{U}\}$  intersects all orbits)

• <, > : an arbitrary inner product

$$\Rightarrow \exists k > 0, \ \exists \varphi \in \operatorname{Aut}(\mathfrak{g}), \ \exists g \in \mathfrak{U}:$$

 $\{\varphi g e_1, \ldots, \varphi g e_n\}$  is orthonormal w.r.t.  $k\langle, \rangle$ .

- A sketch of the proof:
  - By assumption,  $\exists g \in \mathfrak{U} : \langle, \rangle \in \mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}).(g.\langle, \rangle_0).$
  - By definition,  $\exists c\varphi \in \mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}) : \langle, \rangle = (c\varphi g) . \langle, \rangle_0$ .

## §2.2 A procedure to obtain Milnor-type theorems (4/4) Recall:

- $\operatorname{GL}_n(\mathbb{R}) \supset \mathfrak{U}$ : a set of representatives of  $\mathfrak{PM}$
- ⟨,⟩: an arbitrary inner product

 $\Rightarrow \exists k > 0, \exists \varphi \in \operatorname{Aut}(\mathfrak{g}), \exists g \in \mathfrak{U}:$ 

 $\{\varphi g e_1, \ldots, \varphi g e_n\}$  is orthonormal w.r.t.  $k\langle, \rangle$ .

#### **Comment:**

- $\{\varphi g e_1, \ldots, \varphi g e_n\}$  is a generalized Milnor frame.
- Note:  $\varphi$  preserves a bracket product.
- If  $\mathfrak{A}$  can be expressed by l variables  $(l \rightleftharpoons \dim \mathfrak{A})$

 $\Rightarrow$  the bracket relations among them contain only *l* variables.

## §2.3 Three-dimensional case (1/3)

#### **Result of [Hashinaga-T.]:**

• We have obtained Milnor-type theorems for <u>all</u> 3-dimensional solvable Lie algebras.

In this talk, we only consider:

• 
$$\mathfrak{r}'_{3,a} := \operatorname{span}\{e_1, e_2, e_3\} \ (a \ge 0)$$
  
where  $[e_1, e_2] = ae_2 - e_3, \ [e_1, e_3] = e_2 + ae_3.$ 

• Note:  $r'_{3,a}$  is solvable.

• Note:  $\mathfrak{r}'_{3,a}$  is unimodular  $\Leftrightarrow a = 0$ .

## §2.3 Three-dimensional case (2/3)

#### **Prop.** (Hashinaga-T., preprint):

• 
$$\langle, \rangle$$
 : an (arbitrary) inner product on  $\mathfrak{r}'_{3,a}$   
⇒  $\exists k > 0, \exists \lambda \ge 1, \exists \{x_1, x_2, x_3\}$  : o.n.b. w.r.t.  $k\langle, \rangle$  :  
 $[x_1, x_2] = ax_2 - \lambda x_3, \quad [x_1, x_3] = (1/\lambda)x_2 + ax_3.$ 

#### **Proof:**

- $\mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}) \curvearrowright \widetilde{\mathfrak{M}}$ : of cohomogeneity one.
- A set of representatives of  $\mathfrak{PM}$  can be given by  $\mathfrak{U} := \{ \operatorname{diag}(1, 1, 1/\lambda) \mid \lambda \ge 1 \} \cong [1, +\infty).$

#### **Cor. (previously known):**

•  $r'_{3,a}$  admits a left-invariant Einstein metric. (It corresponds to the case  $\lambda = 1$ .)

### §2.3 Three-dimensional case (3/3)

Recall (when a = 0):

• 
$$\langle, \rangle$$
: an (arbitrary) inner product on  $\mathfrak{r}'_{3,0}$   
 $\Rightarrow \exists k > 0, \exists \lambda \ge 1, \exists \{x_1, x_2, x_3\}$ : o.n.b. w.r.t.  $k\langle, \rangle$ :  
 $[x_1, x_2] = -\lambda x_3, \quad [x_1, x_3] = (1/\lambda)x_2.$ 

**Recall (Milnor's Theorem):** 

•  $\langle, \rangle$ : an (arbitrary) inner product on  $\mathfrak{r}'_{3,0}$   $\Rightarrow \exists \lambda_1, \lambda_2 > 0, \exists \{y_1, y_2, y_3\}$ : o.n.b. w.r.t.  $\langle, \rangle$ :  $[y_1, y_2] = 0, [y_2, y_3] = \lambda_1 y_1, [y_3, y_1] = \lambda_2 y_2.$ 

Our theorem recovers Milnor's theorem for  $r'_{3,0}$ :

• It is enough to put (and suitable change of indices)  $y_i := k^{-1/2} x_i, \ \lambda_1 := 0, \ \lambda_2 := \lambda^{-1} k^{-1/2}, \ \lambda_3 := \lambda k^{-1/2}.$ 

## §2.4 Higher-dimensional examples (1/3)

#### **Comment:**

- In general, it is not easy to express PM.
- If dim  $\mathfrak{PM} = 1$  (i.e., cohomogeneity one), then it is easy to handle.

**Recall:** 

- M: a Hadamard manifold (e.g.,  $M = \widetilde{\mathfrak{M}}$ )
- $H \sim M$ : of cohomogeneity one (H: connected)  $\Rightarrow H \setminus M \cong \mathbb{R}$  or  $[0, +\infty)$ .

## §2.4 Higher-dimensional examples (2/3)

#### **Consider:**

• 
$$\mathfrak{g}_{1,1}^n := \operatorname{span}\{e_1, \dots, e_n\},$$
  
where  $[e_i, e_n] = e_i$  (for  $i = 1, \dots, n-2$ ),  
 $[e_{n-1}, e_n] = e_1 + e_{n-1}.$ 

#### Thm. (Taketomi-T., in preparation):

• 
$$\langle , \rangle$$
: an arbitrary inner product on  $\mathfrak{g}_{1,1}^n$   
 $\Rightarrow \exists k > 0, \exists \lambda > 0, \exists \{x_1, \dots, x_n\}$ : o.n.b. w.r.t.  $k\langle , \rangle$ :  
 $[x_i, x_n] = x_i$  (for  $i = 1, \dots, n-2$ ),  
 $[x_{n-1}, x_n] = \lambda x_1 + x_{n-1}$ .

#### Cor.:

• The above  $g_{1,1}^n$  does not admit left-invariant Ricci solitons.

## §2.4 Higher-dimensional examples (3/3)

### **Prop. (Taketomi-T., in preparation):**

- $\mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}_{1,1}^n) \curvearrowright \widetilde{\mathfrak{M}}$  satisfies:
  - The orbit space  $\cong \mathbb{R}_{>0}$ .
  - All orbits  $\mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}_{1,1}^n).\langle,\rangle$  are hypersurfaces in  $\widetilde{\mathfrak{M}}$ .
  - More strongly, all orbits are congruent to each other. (Looks like a horosphere foliation.)

**Comment:** 

- Our expectation:  $\langle,\rangle$  is special  $\Leftrightarrow \mathbb{R}^{\times}Aut(\mathfrak{g}).\langle,\rangle$  is special?
- The above observation certificates this expectation.

(**∄** Ricci soliton, **∄** special orbits)

## **3 Results (for pseudo-Riemannian case)**

## §3.1 Contents

**Comment:** 

• Our method can also be applied to

left-invariant pseudo-Riemannian metrics.

**Contents of this section:** 

- **§3.2:** Pseudo-Riemannian Milnor-type theorems
- §3.3: An example

## **§3.2** Pseudo-Riemannian Milnor-type theorems (1/1)

**Def:** 

- g: (p + q)-dim. Lie algebra
- M̃<sub>(p,q)</sub> := {⟨, ⟩ : an inner product on g with signature (p, q)}
  ≅ GL<sub>p+q</sub>(ℝ)/O(p, q).
  𝔅 𝔅𝔅<sub>(p,q)</sub> := ℝ<sup>×</sup>Aut(𝔅)\M̃<sub>(p,q)</sub> : the moduli space.

#### Thm. (Kubo-Onda-Taketomi-T., in preparation):

- A set of representatives of  $\mathfrak{PM}_{(p,q)}$ 
  - ⇒ a pseudo-Riemannian version Milnor-type theorem(by the same procedure)

Def.:

•  $\mathfrak{g}_{\mathbb{R}H^n} := \operatorname{span}\{e_1, \dots, e_n\}$  with  $[e_1, e_j] = e_j \ (j \ge 2)$ is called the Lie algebra of  $\mathbb{R}H^n$ .

Thm. (Kubo-Onda-Taketomi-T.):

• 
$$\langle, \rangle$$
 : an arbitrary inner product on  $\mathfrak{g}_{\mathbb{R}H^{p+q}}$  with signature  $(p, q)$   
 $\Rightarrow \exists k > 0, \exists \lambda \in \{0, 1, 2\},$   
 $\exists \{x_1, \dots, x_n\}$  : pseudo-o.n.b. w.r.t.  $k\langle, \rangle$  :  
 $[x_1, x_j] = x_j, [x_1, x_n] = -\lambda x_1 + x_n, [x_j, x_n] = -\lambda x_j$   
(for  $j \ge 2$ )

**Idea of Proof:** 

• 
$$\mathfrak{PM}_{(p,q)} := \mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}) \setminus \widetilde{\mathfrak{M}}_{(p,q)}$$
 consists of 3 points.

## §3.3 An example (2/3)

#### **Recall:**

• 
$$\#\mathfrak{PM}_{(p,q)} = 3$$
 for  $\mathfrak{g} = \mathfrak{g}_{\mathbb{R}H^n}$ .

Cor.:

 $\circ \mathfrak{g} := \mathfrak{g}_{\mathbb{R}\mathbf{H}^n}$ 

 $\Rightarrow \forall \langle, \rangle : \text{pseudo-Riemannian, it has a constant curvature } c.$ (c can take any signature, c > 0, c = 0, c < 0)

**Comment:** 

- In Riemannian case, always c < 0 (Milnor 1976).
- Lorentz version of this corollary has been known (Nomizu 1979).
- Our Milnor-type theorem simplifies the proof, and extends it to an arbitrary signature case.

## §3.3 An example (3/3)

### **Question:**

• Why  $\#\mathfrak{PM}_{(p,q)} = 3$  for  $\mathfrak{g} = \mathfrak{g}_{\mathbb{R}H^n}$ ?

### In general:

•  $\mathfrak{PM}_{(p,q)} := \mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g}) \setminus \widetilde{\mathfrak{M}}_{(p,q)} \cong \mathcal{O}(p,q) \setminus (\operatorname{GL}_{p+q}(\mathbb{R})/\mathbb{R}^{\times} \operatorname{Aut}(\mathfrak{g})).$ 

For  $\mathfrak{g} = \mathfrak{g}_{\mathbb{R}\mathbf{H}^n}$ :

- $\mathbb{R}^{\times}$ Aut(g) is parabolic so that  $GL_{p+q}(\mathbb{R})/\mathbb{R}^{\times}$ Aut(g)  $\cong \mathbb{R}P^{p+q-1}$ .
- The above 3 orbits correspond to

 $\{[v] \in \mathbb{R}P^{p+q-1}\}$  with v: timelike, lightlike, spacelike.

#### **Comment:**

- This is a very special case...
- For further studies, we need to know actions on  $GL_{p+q}(\mathbb{R})/O(p,q)$ .

## **4** Summary and Problems

## Summary

**Story:** 

• The space of left-invariant metrics

(both Riemannian and pseudo-Riemannian settings)

- $\Rightarrow$  the moduli space (= the orbit space)
- ⇒ Milnor-type theorems
- $\Rightarrow$  one can examine ALL left-invariant metrics.
- This can be applied to the existence and nonexistence problem of distinguished (e.g., Einstein, Ricci soliton) metrics.

**Point:** 

• Actions on symmetric spaces play important roles.

## **Problems**

### Problem 1:

- A continuation of this study, i.e.,
  - Get more Milnor-type theorems,
  - Study isometric actions on symmetric spaces (both Riemannian and pseudo-Riemannian cases).

Problem 2:

- Apply our method to other geometric structures, e.g.,
  - left-invariant complex structures,
  - left-invariant symplectic structures, ...